

# XuP-Box



XuP-Box has the task of delivering boxes between several storage areas and/or production lines. The autonomous mobile robot is equipped with a lifting platform. It automatically loads/unloads onto passive fork racks.

**50 kg**

Payload

**700/900 mm**

Transfer height

**1.35 m/s**

Max speed



## Lifting platform

Its lifting platform, equipped with a crate centering device, allows it to dock autonomously with passive fork racks.

## Agile

Its small footprint allows for optimal manoeuvrability of the XuP-Box.

## Safe

Designed according to a risk analysis following the Machinery Directive 2006/42/EC and the standard ISO 3691-4.

## Options



Acuity Localization



Visual Warning presence system



Dual zone conveyor



RFID reader



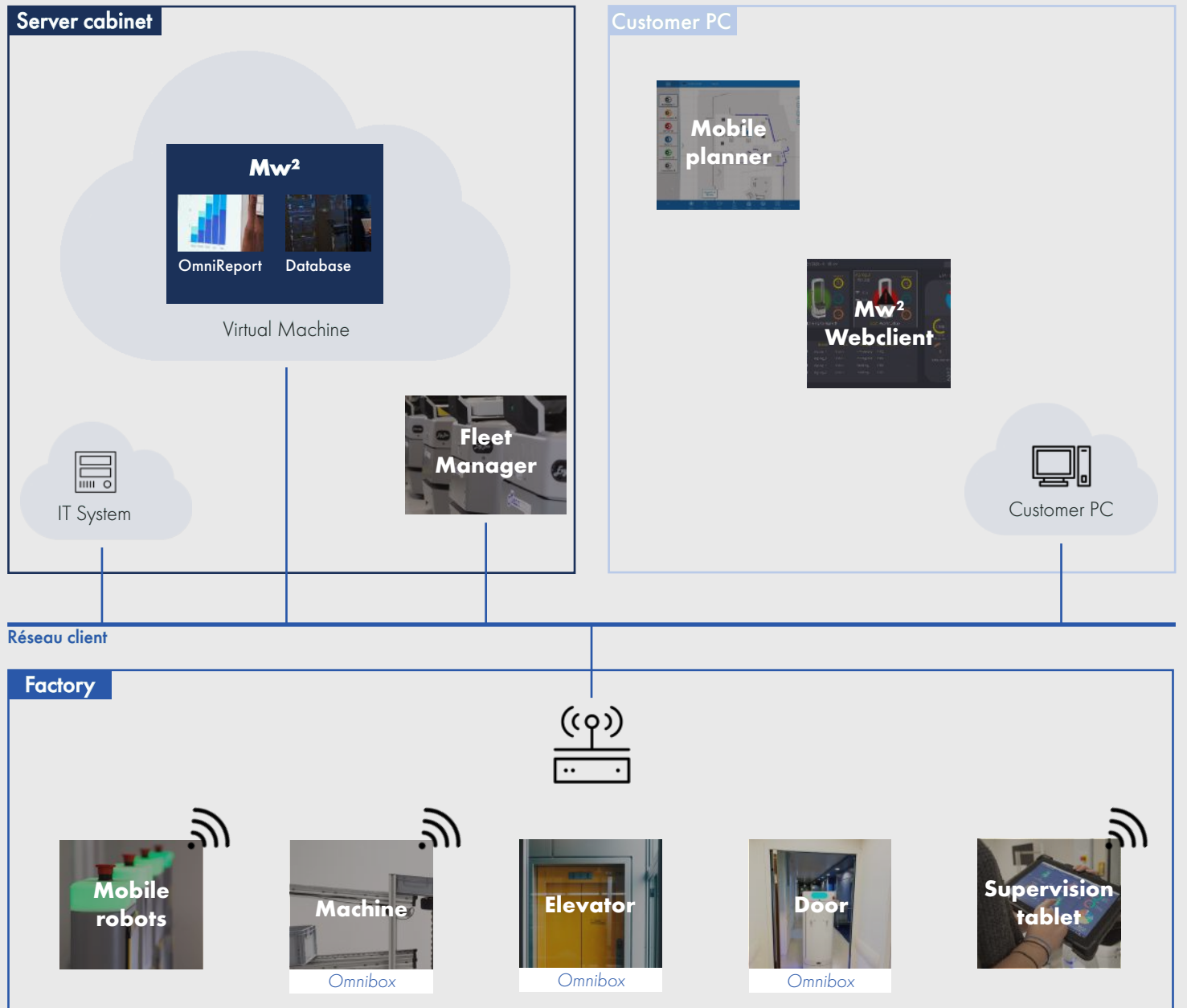
Transfer height adjustable

# A turnkey solution

## Automatic Delivery



## Solution ecosystem



# Technical specifications



## General

Max. speed

1.35m/s (4,85km/h)

Dimension (LxWxh)

720 x 637 x 1631 mm (720mm diameter)

Mechanical weight

90 kg



## Application

Technology

The lifting platform is equipped with an automatic box centering device

Max. transfer height

900 mm

Min. transfer height

700 mm

Up and down system speed

1,5m/minute

Payload

50 kg

Size of the embedded containing

600x400mm, 2(300x400mm)



## Mobility

Navigation

Autonomous routing by localizing with safety scanning laser based on environment mapping.

Environmental map making method

Scan by walking the mobile robot through the environment.

Move

Avoidance and bypassing of obstacles by calculating a new trajectory.



## Human-Machine interface

Touchscreen

7" TFT LCD screen, 800x480 pixels

Manual Mode

Two push buttons to move the robot manually if necessary



## Environnement

Operating temperature range

5 - 40° C

IP Class

IP20

Application environment

Indoor use only, limited dust and oil suspension

Climb grade

Max : 8%

Floor requirement

Linoleum, epoxy or concrete (no water, no oil, no dust)



# Technical specifications



## Safety

*Safety scanning laser*

At front, Class 1  
PLd safety per ISO 13841-1  
15m maximum range  
240° field of view

*Low front laser*

1 at front, Class 1  
4m maximum range  
126° field of view

*Side lasers*

1 on each side of the platform, Class 1  
4m maximum range  
270° field of view

*Emergency Stop*

2 on each side of the robot

*Rear Sonar*

2 at rear, 2m range

*Front bumper*

1 at front of platform, 2 pairs of sensors

*Warning lights*

Light discs on each side  
Upper LED strips

*Speaker and buzzer*

3.5", 80W max



## Battery

*Run time*

± 10 hours

*Recharge time*

± 4 hours

*Voltage*

22-30 VDC LiFePO4

*Capacity*

72 Ah nominal capacity

*Battery life time*

2 000 recharge cycles

*Charging method*

Automatic, manual



## Communication

*WI-FI*

IEEE 802.11 a/b/g

*Bluetooth*

Bluetooth 2.+ERD



## Declaration

*EC Declaration of conformity*

CE Marking

**MeanWHOLE**